FEB 0 3 2003

IN THE UNITED STATES PATENT AND TRADEMARK OFFICE

Applicant:

Thomas R. Corrigan

Examiner: Joseph E. Valenza

Serial No.:

09/905,095

Group Art Unit: 3651

Filed:

July 13, 2001

Docket No.: 56226US002 (M120.134.101)

Date Due:

January 27, 2003 (w/ extension)

Title:

CONTINUOUS MOTION ROBOTIC MANIPULATOR

SUPPLEMENTAL RESPONSE TO ELECTION REQUIREMENT

Commissioner for Patents Washington, D.C. 20231

Dear Sir/Madam:

This is responsive to the Communication mailed November 19, 2002. Please amend the above-identified patent application as follows:

IN THE CLAIMS

Please amend claims 1 and 40 as follows:

RECEIVED

(Amended) A continuous motion robotic device for processing outers, The device comprising:

a first robotic arm;

a second robotic arm;

a third robotic arm;

wherein the robotic arms are each configured to rotate a full 360° and each include an end effector for performing work on an object, and further wherein the robotic arms are arranged about a common axis relative to one another; and

a drive system commonly controlling the robotic arms, the drive system propelling the robotic arms about a central axis.

- 2. The device of claim 1, wherein the robotic arms are identical.
- 3. The device of claim 1, wherein each of the robotic arms includes a first, second and third primary link.